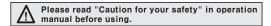
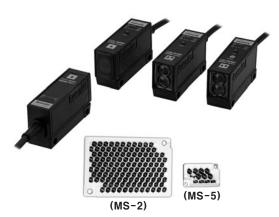
Small and light, common type photoelectric sensor

■ Features

- Easy to mount at a narrow space with small size and light weight.
- Convenient to adjust the sensitivity by external sensitivity adjustment contol.
 (Diffuse reflective type only)
- •Easy to mount by screw type in mounting hole.
- •Reverse power polarity protection circuit.







■ Specifications

Model		BM3M-TDT	BM1M-MDT	BM200-DDT	
Sensing type		Through-beam	Retroreflective	Diffuse reflective	
Sensing distance		3m	(*1) 0.1 to 1m	(* 2) 200mm	
Sensing target		Opaque materials of Min. Ø8mm	Opaque materials of Min. ∮60mm	Translucent, Opaque materials	
Hysteresis				Max. 10% at rated setting distance	
Response time		Max. 3ms			
Power supply		12-24VDC ±10% (Ripple P-P : Max. 10%)			
Current consumption		Max. 45mA Max. 40mA			
Light source		Infrared LED(940nm)			
Sensitivity adjustment		Fixed		Built-in VR	
Operation mode		Dark ON		Light ON	
Control output		• Load voltage : Max. 30VDC	NPN open collector output • Load current : Max. 100mA	• Residual voltage : Max. 1V	
Protection circuit		Reverse polarity protection			
Indication		Operation indicator : Red LED			
Connection		Outgoing cable			
Insulation resistance		Min. 20MΩ (at 500VDC megger)			
Noise strength		$\pm 240 \mathrm{V}$ the square wave noise (pulse width : $1 \mu \mathrm{s}$) by the noise simulator			
Dielectric strength		1,000VAC 50/60Hz for 1minute			
Vibration		1.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours			
Shock		500m/s ² (50G) in X, Y, Z directions for 3 times			
Ambient illumination		Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x			
Ambient temperature		-10 to 60℃ (at non-freezing status), Storage: -25 to 70℃			
Ambient humidity		35 to 85%RH, Storage : 35 to 85%RH			
Material		Case: ABS, Lens: PMMA			
Cable		3P(2P for Transmitted beam type), ∅4mm, Length: 2m			
Accessories	Individual		Reflector(MS-2)	Adjustment driver	
	Common	Fixing bracket, Bolts/nuts			
Approval		C€			
Unit weight		Approx. 170g	Approx. 105g	Approx. 88g	

^{*(★1)}It is mounting distance between sensor and reflector MS-2 and it is same when MS-5 is used. It is detectable under 0.1m.

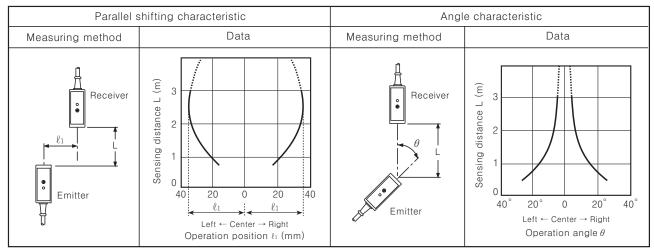
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^{*(*2)}It is for Non-glossy white paper (100×100mm)

Amplifier Built-in Type for General Purpose

■ Feature data

●BM3M-TDT



©Retroreflective

●BM1M-MDT

Parallel s	shifting characteristic	Sensor angle characteristic	
Measuring method	Data	Measuring method	Data
Reflector(MS-2)	(\mathbb{E}_{0}) 0 0 0 0 0 0 0 0 0 0	Reflector(MS-2)	(B) 100 Sequence (B)

©Retroreflective

●BM1M-MDT

ODiffuse reflective

●BM200-DDT

Sensing area characteristic				
Measuring method	Data			
Standard sensing target : Non-glossy white paper 200×200mm	$\begin{array}{c} (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B}}) \\ (\widetilde{\mathbb{B})} \\$			

(A) Photo electric sensor

(B) Fiber optic sensor

> (C) Door/Area sensor

> (D) Proximity sensor

> (E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

(K) Timer

(L) Panel

meter
(M)
Tacho/
Speed/
Pulse

(N) Display unit

meter

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

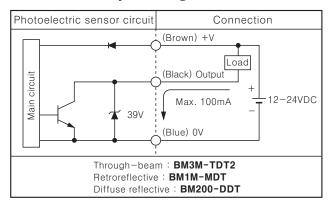
(S) Field network device

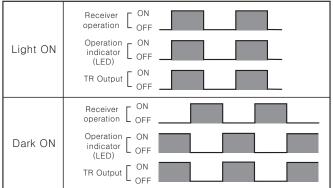
(T) Production stoppage models & replacement

Autonics A-30

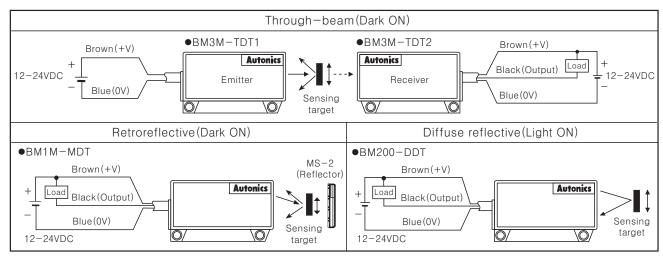
■Control output diagram

Operation mode

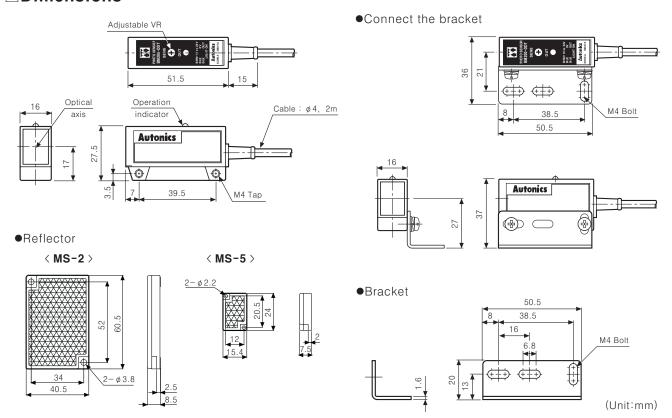




Connections



Dimensions



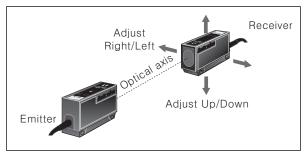
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Amplifier Built-in Type for General Purpose

Mounting and sensitivity adjustment

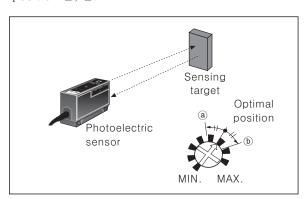
OThrough-beam type

- 1. Supply the power to the photoelectric sensor, after set the emitter and the receiver facing each other.
- 2. Set the receiver in the middle of the operation range of indicator adjusting the receiver or the emitter right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If the sensing target is translucent body or smaller than \$\phi 8mm\$, it can be missed by sensor because light penetrate it.



ODiffuse reflective type

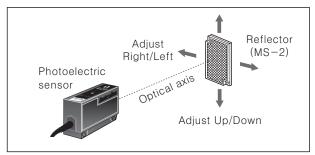
- 1. The sensitivity should be adjusted depending on a sensing target or mounting place.
- 2. Set the target at a position to be detected by the beam, then turn the adjuster until position ⓐ where the indicator turns on from min. position of the adjuster.
- 3. Take the target out of the sensing area, then turn the adjuster until position ⓑ where the indicator turns on. If the indicator does not turn on, Max. position is position ⓑ.
- 4. Set the adjuster at the center of two switching position (a), (b).



*The sensing distance indicated on specification chart is for 200×200mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.

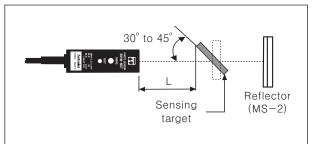
©Retroreflective type

- 1. Supply the power to the photoelectric sensor, after set the emitter and the reflector(MS-2) facing to each other.
- 2. Set the reflector or photoelectric sensor in the middle of the operation range of indicator adjusting the mirror or the sensor right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.



*If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when thr target is nead to photoelectric sensor.

Therefore enough space between the target should be used and photoelectric sensor or the surface of target should be installed at an angle of 30° to 45° against optical axis.



*If the installing place is too small, please use MS-5 instead of MS-2 for same sensing distance.



(A) Photo electric

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meter
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Pulse

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(P) Switching power supply

(Q) Stepping motor & Driver & Controller

(R) Graphic/ Logic panel

(S) Field network device

(T) Production stoppage models & replacement

Autonics A-32